

Product datasheet

Specifications



Variable speed drive. Altivar
Process ATV600. ATV630. 55kW/
75 hp. 500V/690 V. IP00

ATV630D55Y6

Price: 169,455.00 ZAR

Main

Range Of Product	Altivar Process ATV600
Product Or Component Type	Variable speed drive
Product Specific Application	Process and utilities
Device Short Name	ATV630
Variant	Standard version
Product Destination	Asynchronous motors Synchronous motors
Emc Filter	Integrated with 25 m conforming to IEC 61800-3 category C3
Ip Degree Of Protection	IP00 conforming to IEC 61800-5-1 IP00 conforming to IEC 60529 IP20 (with kit VW3A9706) conforming to IEC 61800-5-1 IP20 (with kit VW3A9706) conforming to IEC 60529
[Us] Rated Supply Voltage	500...690 V
Type Of Cooling	Forced convection
Supply Frequency	50...60 Hz - 5...5 %
[Us] Rated Supply Voltage	500...690 V - 15...10 %
Motor Power Kw	45 kW at 500 V (normal duty) 37 kW at 500 V (heavy duty) 55 kW at 690 V (normal duty) 45 kW at 690 V (heavy duty)
Motor Power Hp	60 hp at 500 V normal duty 50 hp at 500 V heavy duty 75 hp at 690 V normal duty 60 hp at 690 V heavy duty
Line Current	65.5 A at 500 V (normal duty) 62.5 A at 690 V (normal duty) 55.6 A at 500 V (heavy duty) 54.4 A at 690 V (heavy duty)
Prospective Line Isc	70 kA
Apparent Power	74.7 kVA at 690 V (normal duty) 65 kVA at 690 V (heavy duty)
Continuous Output Current	66 A at 2.5 kHz for normal duty 55 A at 2.5 kHz for heavy duty
Asynchronous Motor Control Profile	Variable torque standard Optimized torque mode Constant torque standard
Synchronous Motor Control Profile	Permanent magnet motor Synchronous reluctance motor
Speed Drive Output Frequency	0.1...500 Hz
Nominal Switching Frequency	2.5 kHz

Excluding VAT and subject to change. Please check with your local distributor through "Where to buy"

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Switching Frequency	1...4.9 kHz adjustable 2.5...4.9 kHz with derating factor
Safety Function	STO (safe torque off) SIL 3
Discrete Input Logic	16 preset speeds
Communication Port Protocol	Ethernet Modbus serial Modbus TCP
Option Card	Slot A: communication module, Profibus DP V1 Slot A: communication module, PROFINET Slot A: communication module, DeviceNet Slot A: communication module, Modbus TCP/EtherNet/IP Slot A: communication module, CANopen daisy chain RJ45 Slot A: communication module, CANopen SUB-D 9 Slot A: communication module, CANopen screw terminals Slot A/slot B: digital and analog I/O extension module Slot A/slot B: output relay extension module Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link Communication module, BACnet MS/TP Communication module, Ethernet Powerlink

Complementary

Mounting Mode	Wall mount
Maximum Transient Current	72.6 A during 60 s (normal duty) 82.5 A during 60 s (heavy duty)
Network Number Of Phases	3 phases
Discrete Output Number	0
Discrete Output Type	Relay outputs R1A, R1B, R1C 250 V AC 3000 mA Relay outputs R1A, R1B, R1C 30 V DC 3000 mA Relay outputs R2A, R2C 250 V AC 5000 mA Relay outputs R2A, R2C 30 V DC 5000 mA Relay outputs R3A, R3C 250 V AC 5000 mA Relay outputs R3A, R3C 30 V DC 5000 mA
Output Voltage	<= power supply voltage
Permissible Temporary Current Boost	1.1 x I _n during 60 s (normal duty) 1.5 x I _n during 60 s (heavy duty)
Motor Slip Compensation	Adjustable Automatic whatever the load Not available in permanent magnet motor law Can be suppressed
Acceleration And Deceleration Ramps	Linear adjustable separately from 0.01...9999 s S, U or customized
Physical Interface	Ethernet 2-wire RS 485
Braking To Standstill	By DC injection
Protection Type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive

Transmission Rate	10, 100 Mbits 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps
Frequency Resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
Transmission Frame	RTU
Electrical Connection	Control: removable screw terminals 0.5...1.5 mm²/AWG 20...AWG 16 Line side: screw terminal 25...50 mm²/AWG 4...AWG 1 Motor: screw terminal 25...50 mm²/AWG 4...AWG 1
Connector Type	RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP RJ45 (on the remote graphic terminal) for Modbus serial
Data Format	8 bits, configurable odd, even or no parity
Type Of Polarization	No impedance
Exchange Mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP
Number Of Addresses	1...247 for Modbus serial
Method Of Access	Slave Modbus TCP
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local Signalling	3 LEDs for local diagnostic 3 LEDs (dual colour) for embedded communication status 4 LEDs (dual colour) for communication module status 1 LED (red) for presence of voltage
Width	331 mm
Height	630 mm
Depth	297 mm
Net Weight	53 kg
Analogue Input Number	3
Analogue Input Type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 31.5 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits AI2 voltage analog input: - 10...10 V DC, impedance: 31.5 kOhm, resolution 12 bits
Discrete Input Number	8
Discrete Input Type	DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V)
Input Compatibility	DI1...DI6: discrete input level 1 PLC conforming to IEC 61131-2 DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2
Discrete Input Logic	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1)
Analogue Output Number	2
Analogue Output Type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA, resolution 10 bits Software-configurable current DQ-, DQ+: 30 V DC Software-configurable current DQ-, DQ+: 100 mA
Sampling Duration	2 ms +/- 0.5 ms (DI1...DI4) - discrete input 5 ms +/- 1 ms (DI5, DI6) - discrete input 5 ms +/- 0.1 ms (AI1, AI2, AI3) - analog input 10 ms +/- 1 ms (AO1) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AO1, AO2 for a temperature variation 60 °C analog output

Linearity Error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AO1, AO2: +/- 0.2 % for analog output
Relay Output Number	3
Relay Output Type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles
Refresh Time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Minimum Switching Current	Relay output R1, R2, R3: 5 mA at 24 V DC
Maximum Switching Current	Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Isolation	Between power and control terminals
Maximum Output Frequency	500 kHz
Maximum Input Current	65.5 A
Quantity Per Set	1
Enclosure Mounting	Wall mounted

Environment

Insulation Resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise Level	52 dB conforming to 86/188/EEC
Power Dissipation In W	Natural convection: 227 W at 500 V, switching frequency 2.5 kHz Forced convection: 858 W at 500 V, switching frequency 2.5 kHz
Volume Of Cooling Air	406 m3/h
Operating Position	Vertical +/- 10 degree
Maximum Thdi	<48 % with external line choke conforming to IEC 61000-3-12
Electromagnetic Compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Pollution Degree	2 conforming to IEC 61800-5-1
Vibration Resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock Resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Relative Humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient Air Temperature For Operation	-15...50 °C (without derating) 50...60 °C (with derating factor)
Ambient Air Temperature For Storage	-40...70 °C
Operating Altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Product Certifications	UL CSA TÜV
Marking	CE

Standards	UL 508C
	IEC 61800-3
	EN/IEC 61800-3 environment 2 category C3
	IEC 61800-5-1
	IEC 61000-3-12
	IEC 60721-3
	IEC 61508
	IEC 13849-1
Overvoltage Category	III
Regulation Loop	Adjustable PID regulator
Noise Level	56 dB
Pollution Degree	2

Packing Units

Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	58.0 cm
Package 1 Width	44.0 cm
Package 1 Length	111.0 cm
Package 1 Weight	68.0 kg

Sustainability

Green Premium™ label is Schneider Electric’s commitment to delivering products with best-in-class environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO₂ products.

Guide to assessing product sustainability is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

[Learn more about Green Premium >](#)

[Guide to assess a product’s sustainability >](#)



Transparency RoHS/REACH

Resource performance

 Upgraded Components Available

Well-being performance

 Mercury Free

 Rohs Exemption Information [Yes](#)

Certifications & Standards

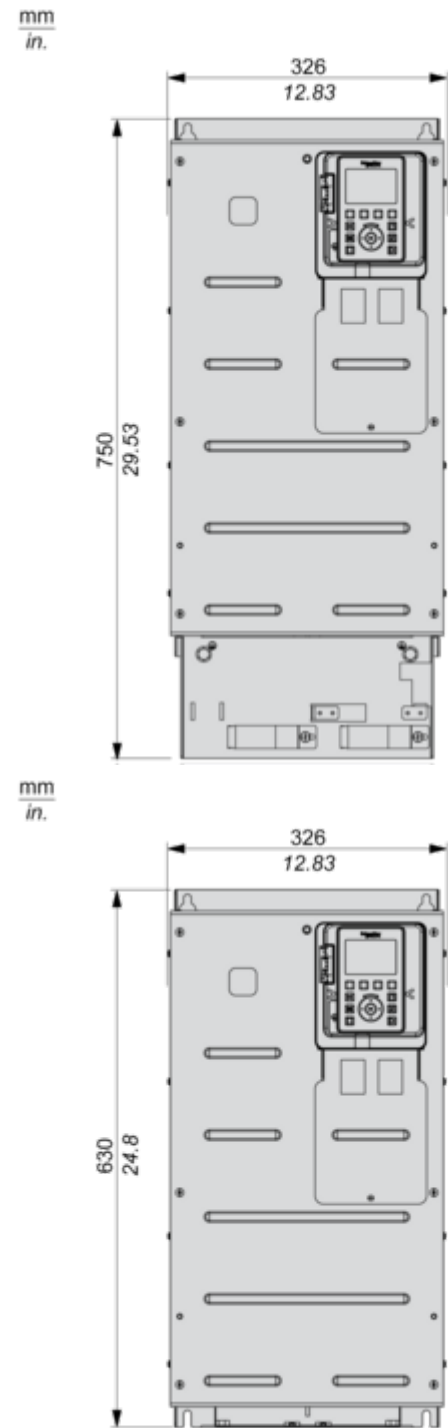
Reach Regulation	REACH Declaration
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)
China Rohs Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
Circularity Profile	End of Life Information

Dimensions Drawings

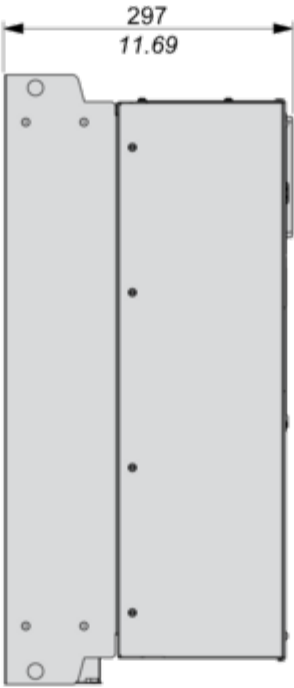
Dimensions

Drives without Top Cover

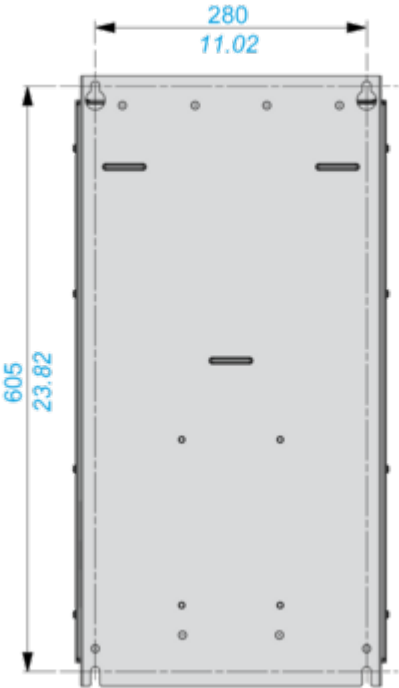
Front View with EMC Plate, Front, Left and Rear Views without EMC Plate



mm
in.

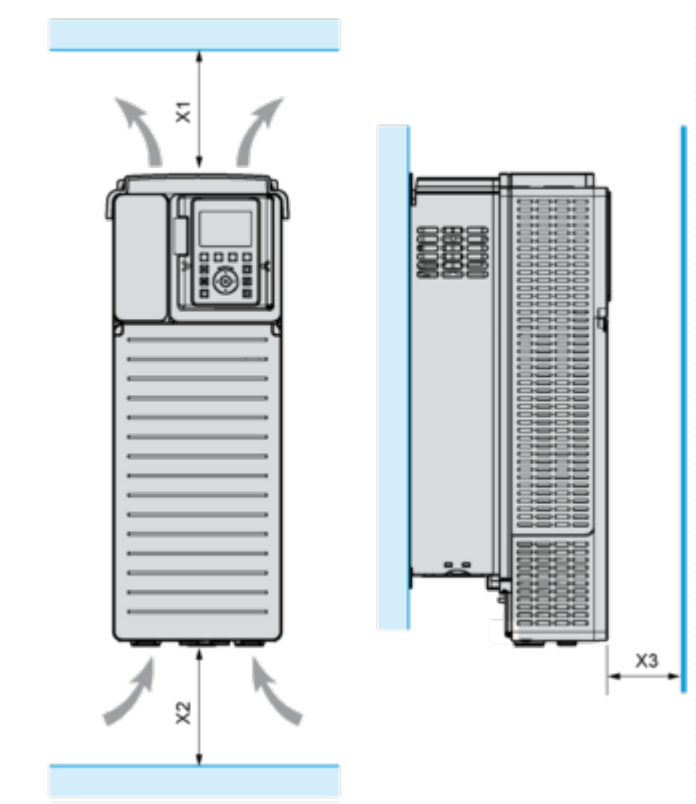


mm
in.



Mounting and Clearance

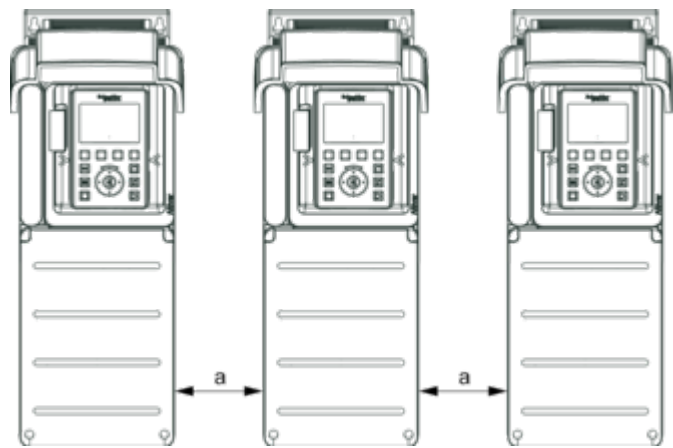
Clearances



X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

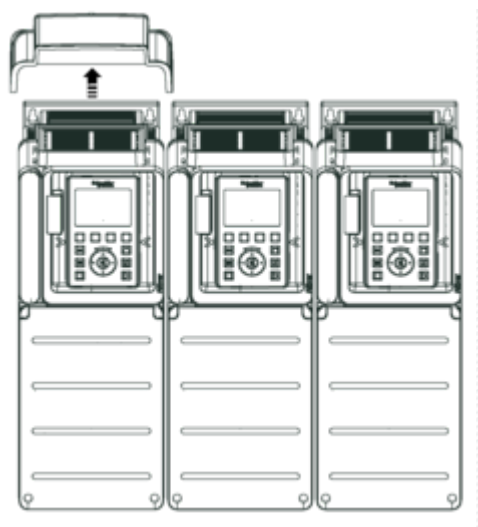
Mounting Types

Mounting Type A: Individual IP21

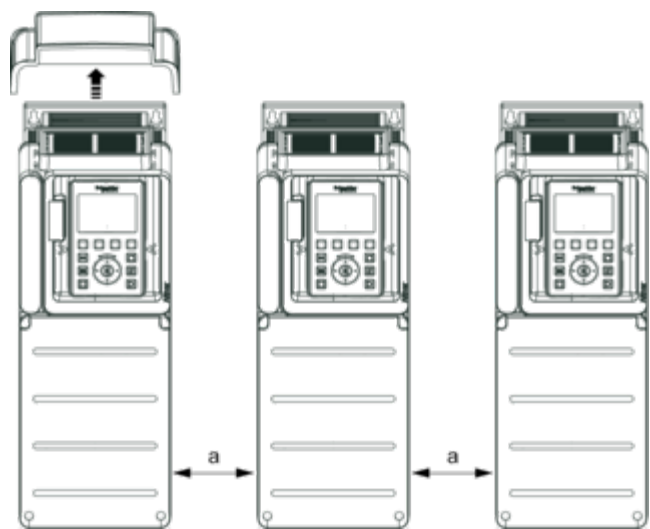


$a \geq 0$

Mounting Type B: Side by Side IP20



Mounting Type C: Individual IP20

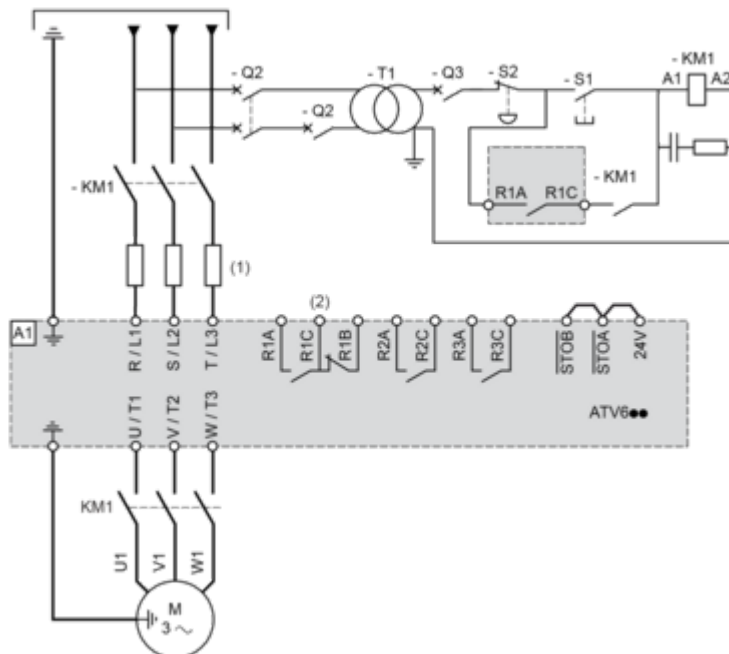


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Connections and Schema

Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Line Contactor

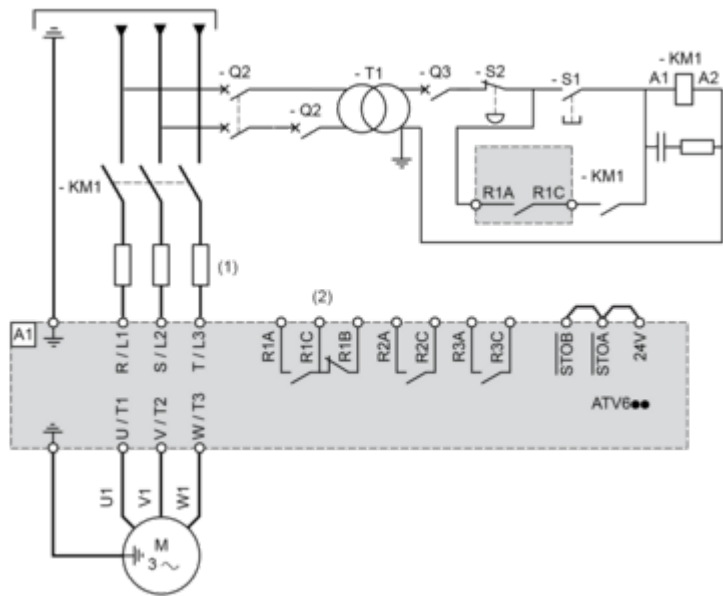
Q2, Q3 : Circuit breakers

S1, S2 : Pushbuttons

T1 : Transformer for control part

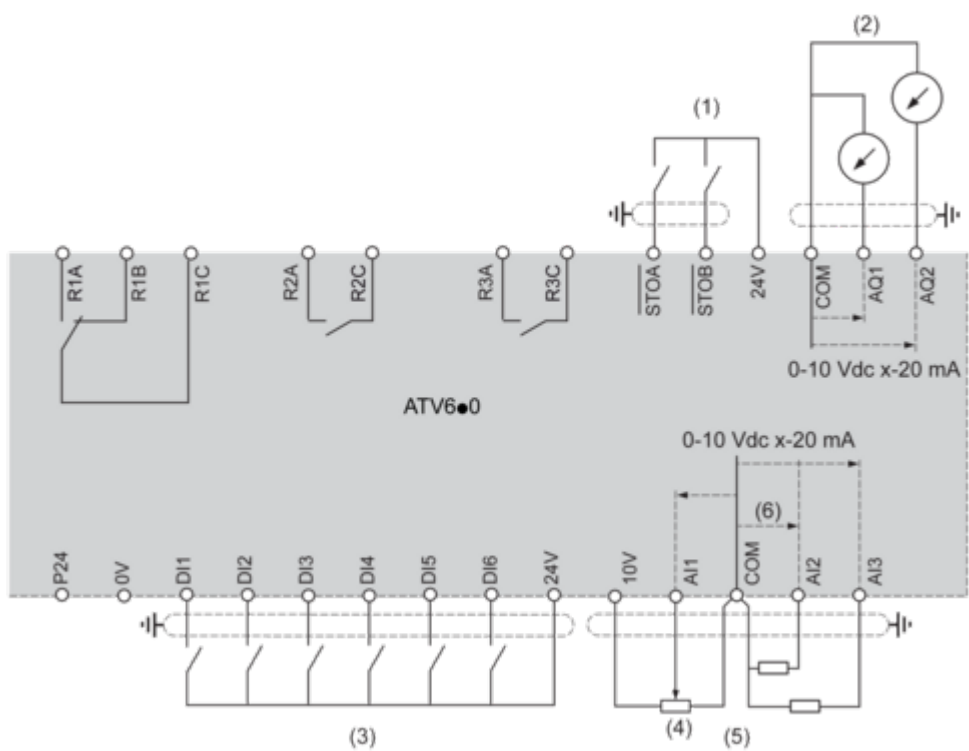
Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
- (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive
- KM1 : Contactor

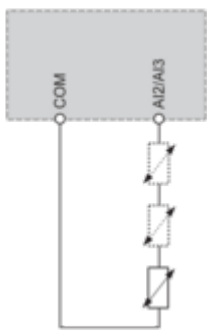
Control Block Wiring Diagram



- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- R1A, R1B, R1C : Fault relay
- R2A, R2C : Sequence relay
- R3A, R3C : Sequence relay

Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

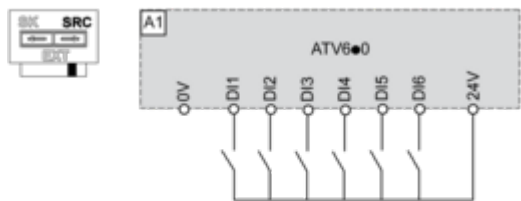


Sink / Source Switch Configuration

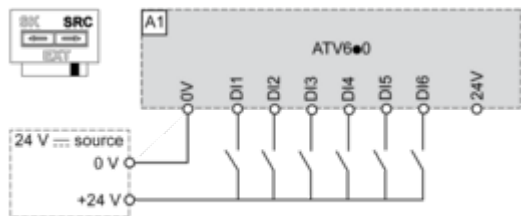
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

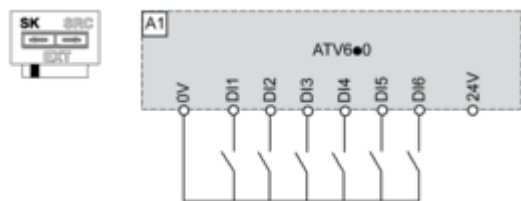
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



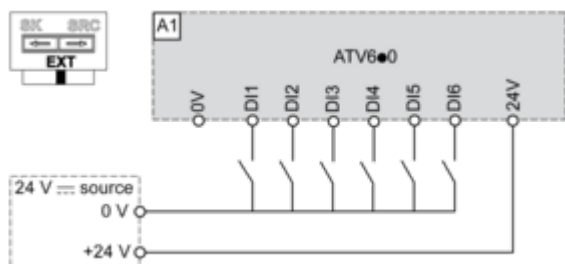
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DIs



Performance Curves

Derating Curves

