

# Product datasheet

Specifications



## Low Harmonic Drive System ATV680 - 132/110kW - 400 V - IP23

ATV680C13Q4X1

**Price: 709,035.09 ZAR**

### Main

Device Short Name	ATV680
Product Destination	Asynchronous motors Synchronous motors
Ip Degree Of Protection	IP23 conforming to IEC 61800-5-1
Supply Frequency	50/60 Hz +/- 5 %
Network Number Of Phases	3 phases
Range Of Product	Altivar Process ATV600
Product Or Component Type	Variable speed drive
Product Specific Application	Process and utilities
Communication Port Protocol	EtherNet/IP Modbus TCP Modbus serial
[Us] Rated Supply Voltage	380...415 V - 10...6 %
Motor Power Kw	132 kW for normal duty 110 kW for heavy duty

### Complementary

Provided Equipment	Enclosure Spacial SF Graphical operating panel in the enclosure door Main switch Semiconductor fuses Clean power filter with EMC filter Active infeed converter module Frequency inverter Terminal block main supply Terminal block motor
Colour Of Enclosure	Light grey (RAL 7035)
Type Of Cooling	Forced convection
Output Voltage	<= power supply voltage
Permissible Temporary Current Boost	1.1 x In during 60 s (normal duty) 1.5 x In during 60 s (heavy duty)
Speed Drive Output Frequency	0.1...500 Hz
Speed Accuracy	V/f mode: slip frequency VC without feedback: 0.3 x slip frequency
Continuous Output Current	250 A at 2.5 kHz for normal duty 211 A at 2.5 kHz for heavy duty
Energy Efficiency Ratio	0.965

Excluding VAT and subject to change. Please check with your local distributor through "Where to buy"

<b>Power Dissipation In W</b>	5110 W, total (normal duty) 4200 W, total (heavy duty) 660 W, control part (normal duty) 540 W, control part (heavy duty)
<b>Volume Of Cooling Air</b>	1160 m3/h for power 140 m3/h for control
<b>Prospective Line Isc</b>	50 kA for 100 ms
<b>Motor Recommended Cable Cross Section</b>	1 x (3 x 150 mm <sup>2</sup> ) (normal duty) 2 x (3 x 70 mm <sup>2</sup> ) (normal duty) 1 x (3 x 120 mm <sup>2</sup> ) (heavy duty) 2 x (3 x 50 mm <sup>2</sup> ) (heavy duty)
<b>Height</b>	2150 mm
<b>Depth</b>	664 mm
<b>Safety Function</b>	STO (safe torque off), level SIL 3 for <= 100 ms
<b>Protection Type</b>	Motor: thermal protection Motor: safe torque off Motor: motor phase break Drive: thermal protection Drive: safe torque off Drive: overheating Drive: overcurrent (between output phases and earth) Drive: overload (output) Drive: short-circuit protection Drive: motor phase break Drive: overvoltage (DC bus) Drive: line supply overvoltage Drive: line supply undervoltage Drive: line supply phase loss Drive: overspeed Drive: break on the control circuit Drive: short-circuit protection with semi-conductor fuse (main supply) Drive: fan monitoring
<b>Frequency Resolution</b>	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
<b>Connector Type</b>	RJ45 (on the control block) for Modbus serial RJ45 (on the control block) for Ethernet IP/Modbus TCP
<b>Physical Interface</b>	2-wire RS 485 for Modbus serial
<b>Transmission Frame</b>	RTU for Modbus serial
<b>Transmission Rate</b>	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
<b>Exchange Mode</b>	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
<b>Data Format</b>	8 bits, configurable odd, even or no parity for Modbus serial
<b>Type Of Polarization</b>	No impedance for Modbus serial
<b>Number Of Addresses</b>	1...247 for Modbus serial
<b>Supply</b>	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
<b>Local Signalling</b>	LCD display unit front door operation function, status and configuration
<b>Input Compatibility</b>	DI1...DI6: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2
<b>Discrete Input Logic</b>	Positive logic (source) (DI1...DI6), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI6), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI5, DI6), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)

<b>Sampling Duration</b>	2 ms +/- 0.5 ms (DI1...DI4) - discrete input 5 ms +/- 1 ms (DI5, DI6) - discrete input 5 ms +/- 1 ms (AI1, AI2, AI3) - analog input 10 ms +/- 1 ms (AQ1, AQ2) - analog output
<b>Accuracy</b>	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
<b>Linearity Error</b>	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
<b>Refresh Time</b>	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
<b>Isolation</b>	Between power and control terminals
<b>Insulation Resistance</b>	> 1 MOhm 500 V DC for 1 minute to earth
<b>Relative Humidity</b>	5...95 % without condensation conforming to IEC 60068-2-3
<b>Option Card</b>	Slot A: communication module, Profibus DP V1 Slot A: communication module, PROFINET Slot A: communication module, DeviceNet Slot A: communication module, Modbus TCP/EtherNet/IP Slot A: communication module, CANopen daisy chain RJ45 Slot A: communication module, CANopen SUB-D 9 Slot A: communication module, CANopen screw terminals Slot A/slot B: digital and analog I/O extension module Slot A/slot B: output relay extension module
<b>Discrete Input Number</b>	8
<b>Discrete Input Type</b>	DI1...DI6 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI5, DI6 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2200 kOhm
<b>Discrete Input Logic</b>	16 preset speeds
<b>Analogue Input Number</b>	3
<b>Analogue Input Type</b>	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits
<b>Analogue Output Number</b>	2
<b>Analogue Output Type</b>	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA, resolution 10 bits
<b>Relay Output Number</b>	3
<b>Relay Output Type</b>	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles
<b>Maximum Switching Current</b>	Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
<b>Minimum Switching Current</b>	Relay output R1, R2, R3: 5 mA at 24 V DC
<b>Method Of Access</b>	Slave Modbus TCP
<b>Asynchronous Motor Control Profile</b>	Variable torque standard Constant torque standard Optimized torque mode
<b>Synchronous Motor Control Profile</b>	Permanent magnet motor
<b>Acceleration And Deceleration Ramps</b>	Linear adjustable separately from 0.01 to 9000 s S, U or customized
<b>Motor Slip Compensation</b>	Can be suppressed Adjustable Automatic whatever the load Not available in permanent magnet motor law

<b>Switching Frequency</b>	2...8 kHz adjustable with derating factor
<b>Nominal Switching Frequency</b>	2.5 kHz
<b>Braking To Standstill</b>	By DC injection
<b>Line Current</b>	208 A at 400 V (normal duty) 174 A at 400 V (heavy duty)
<b>Apparent Power</b>	144 kVA at 400 V (normal duty) 121 kVA at 400 V (heavy duty)
<b>Maximum Transient Current</b>	275 A during 60 s per 10 min (normal duty) 317 A during 60 s per 10 min (heavy duty)
<b>Short-Circuit Protection</b>	Upstream: 300 A gG fuse (normal duty) Upstream: 300 A gG fuse (heavy duty) Internal: 315 A aR fuse
<b>Electrical Connection</b>	Removable screw terminals, clamping capacity: 0.5...1.5 mm <sup>2</sup> for control M12 bar for main supply M12 bar for motor
<b>Cable Entry</b>	Bottom
<b>Width</b>	600 mm
<b>Net Weight</b>	400 kg

## Environment

<b>Noise Level</b>	70 dB conforming to 86/188/EEC - physical agents (noise) directive
<b>Emc Filter</b>	Integrated conforming to EN/IEC 61800-3, category C3, shielded cable with 50 m Integrated conforming to EN/IEC 61800-3, category C4, unshielded cable with 80 m
<b>Pollution Degree</b>	2 conforming to EN/IEC 61800-5-1
<b>Vibration Resistance</b>	1.5 mm peak to peak (f= 3...10 Hz) conforming to IEC 60068-2-6 0.6 gn (f= 10...200 Hz) conforming to IEC 60068-2-6 3M3 conforming to IEC 60721-3-3
<b>Shock Resistance</b>	4 gn for 11 ms conforming to IEC 60068-2-27 3M2 conforming to IEC 60721-3-3
<b>Operating Altitude</b>	< 1000 m without derating 1000...2000 m with current derating 1 % per 100 m 2000...3800 m with current derating 1 % per 100 m for TT earthing system 2000...3800 m with current derating 1 % per 100 m for TN earthing system 2000...3800 m with current derating 1 % per 100 m for IT earthing system 3800...4800 m with current derating 1 % per 100 m for TT earthing system 3800...4800 m with current derating 1 % per 100 m for TN earthing system
<b>Environmental Characteristic</b>	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3 Humidity resistant class 3K3 conforming to EN/IEC 60721-3-3
<b>Product Certifications</b>	ATEX C-Tick EAC
<b>Operating Position</b>	Vertical +/- 10 degree
<b>Marking</b>	CE
<b>Standards</b>	EN/IEC 60204-1 EN/IEC 61800-2 EN/IEC 61800-3 EN/IEC 61800-5-1
<b>Maximum Thdi</b>	<5 % full load conforming to IEEE 519
<b>Assembly Style</b>	In floor-standing enclosure low harmonic version

<b>Electromagnetic Compatibility</b>	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 $\mu$ s - 8/20 $\mu$ s surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
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<b>Overvoltage Category</b>	III
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<b>Ambient Air Temperature For Operation</b>	-10...0 °C without derating (with option enclosure heating) 0...40 °C without derating 40...50 °C with derating factor
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<b>Ambient Air Temperature For Storage</b>	-25...70 °C
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## Packing Units

<b>Unit Type Of Package 1</b>	PCE
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<b>Number Of Units In Package 1</b>	1
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<b>Package 1 Height</b>	215 cm
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<b>Package 1 Width</b>	66.9 cm
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<b>Package 1 Length</b>	60 cm
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<b>Package 1 Weight</b>	445 kg
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## Sustainability

**Green Premium™ label** is Schneider Electric's commitment to delivering products with best-in-class environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO<sub>2</sub> products.

**Guide to assessing product sustainability** is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

[Learn more about Green Premium >](#)

[Guide to assess a product's sustainability >](#)



Take-back

## Resource performance

✓ Take-Back Program Available

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## Well-being performance

✓ Mercury Free

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✓ Rohs Exemption Information Yes

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Reach Regulation [REACH Declaration](#)

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Eu Rohs Directive Pro-active compliance (Product out of EU RoHS legal scope)

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China Rohs Regulation [China RoHS declaration](#)

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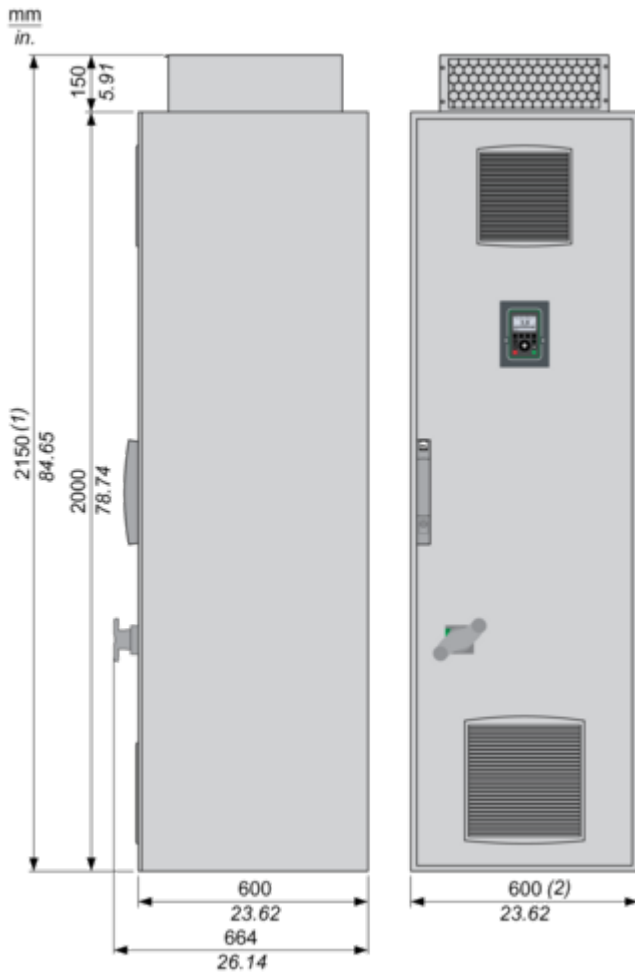
Weee The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

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Dimensions Drawings

Dimensions

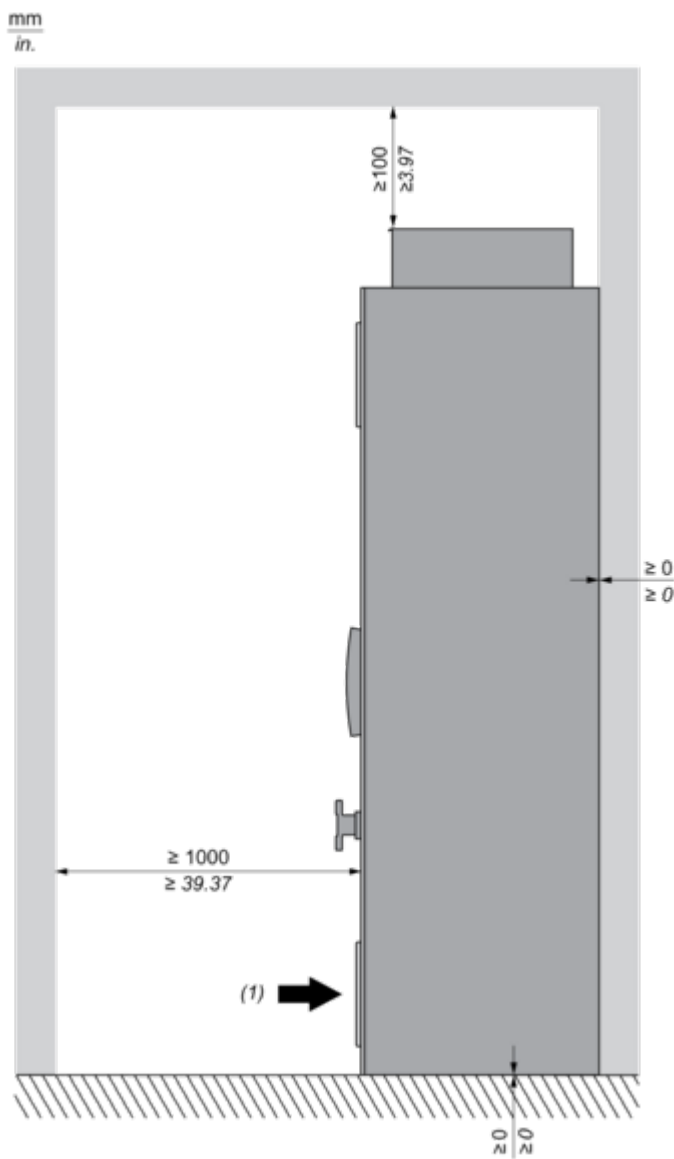
Right and Front Views



- (1) + 200 mm/7.87 in. with option enclosure plinth or increased protection degree IP54.
- (2) + 400 mm/15.74 in. with option connection enclosure cable from top/bottom.

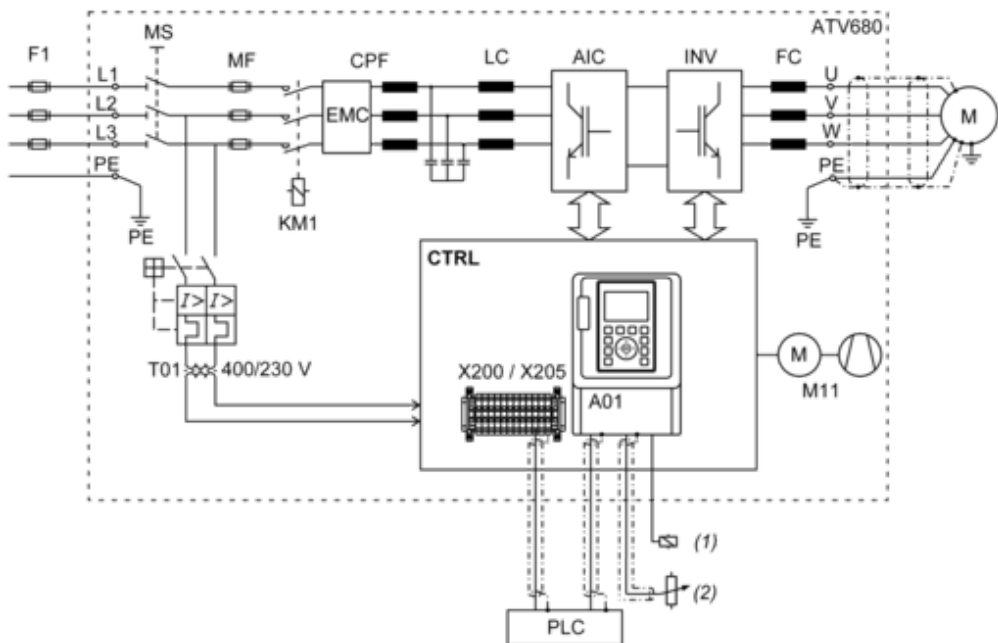
Mounting and Clearance

Mounting and Clearance



Connections and Schema

Typical Wiring Diagram of the Frequency Inverter



**F1** : External pre-fuse or circuit breaker

**MS** : Built-in main switch

**T01** : Control transformer 400 / 230 V AC

**MF** : aR fuses

**CPF** : Clean Power Filter with integrated EMC filter

**LC** : Line reactor Chokes

**AIC** : Active Infeed Converter module

**INV** : Inverter module

**FC** : dv/dt filter (from 200 kW the dv/dt filter choke 150 m is built-in as standard)

**CTRL** : Control panel

**A01** : Control terminals at the control block

**X200 / X205** : Control terminals at the control panel (depending on the chosen options)

**M11** : Fan in enclosure door

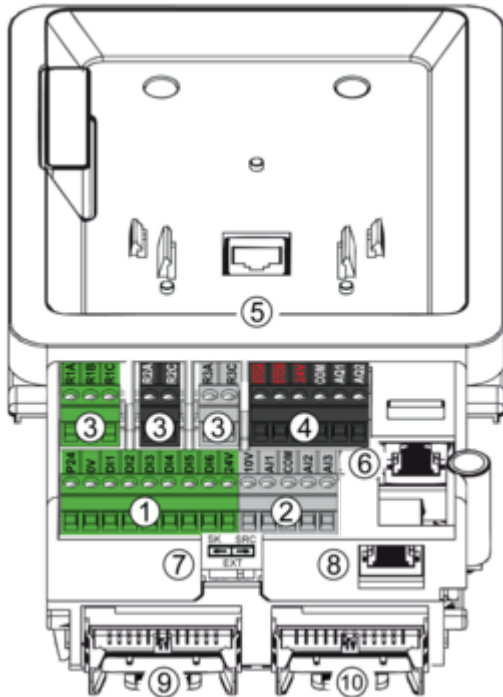
**KM1** : Line contactor

(1) Relay control

(2) Reference value

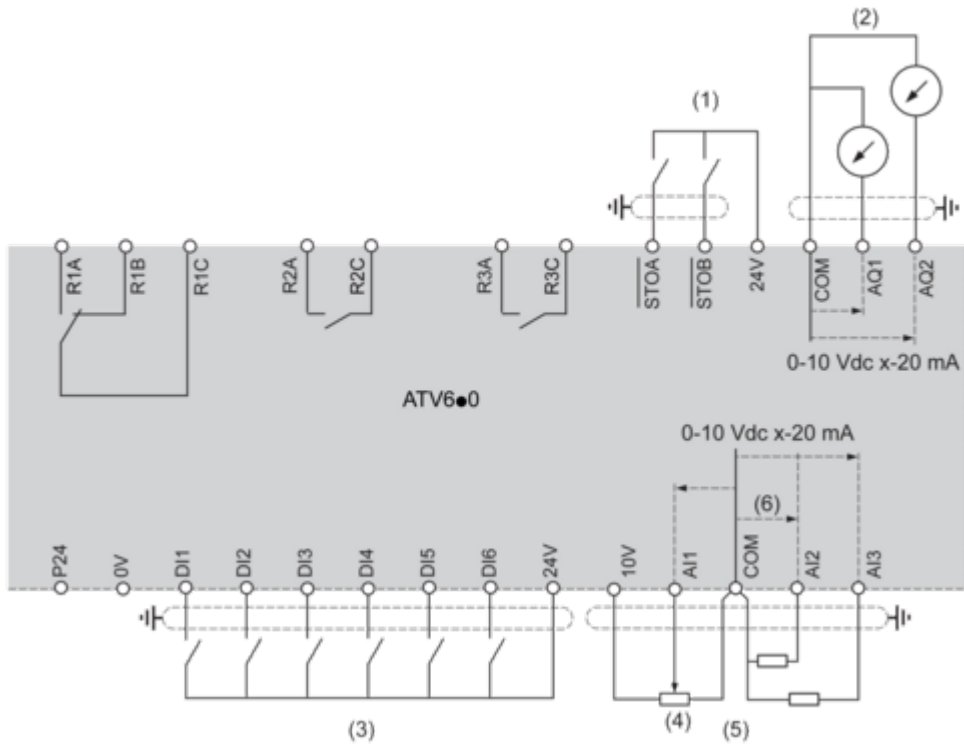
Structure of the Control Block

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- (1) Digital inputs
- (2) Analog inputs
- (3) Relay outputs
- (4) STO (Safe Torque Off) and analog outputs
- (5) RJ45 port for door mounting kit of the graphic keypad
- (6) RJ45 port for Ethernet IP or Modbus TCP
- (7) Sink-Ext-Source selector switch (see switch configuration below)
- (8) RJ45 port for serial Modbus
- (9) Slot for I/O expansion card
- (10) Slot for fieldbus or I/O expansion card

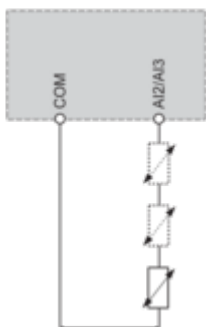
Control Block Wiring Diagram



- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- R1A, R1B, R1C : Fault relay
- R2A, R2C : Sequence relay
- R3A, R3C : Sequence relay

Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

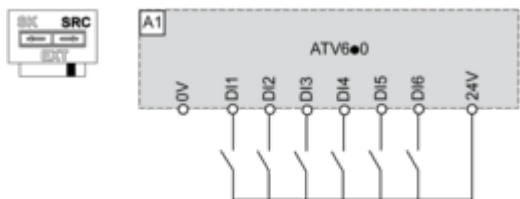


**Sink / Source Switch Configuration**

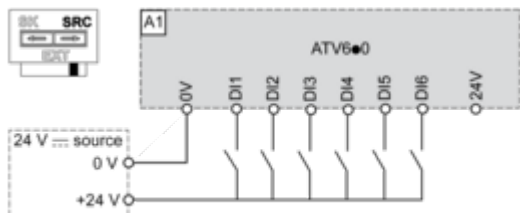
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

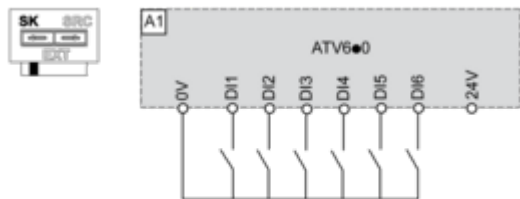
**Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs**



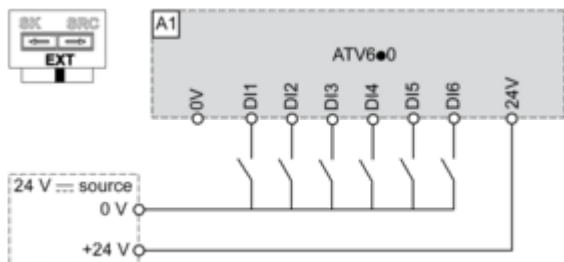
**Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs**



**Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs**



**Switch Set to EXT Position Using an External Power Supply for the DIs**

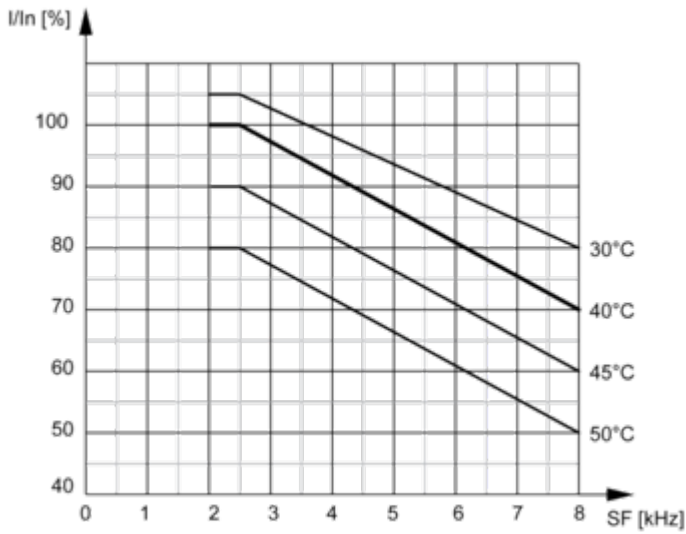


Performance Curves

Derating Curves

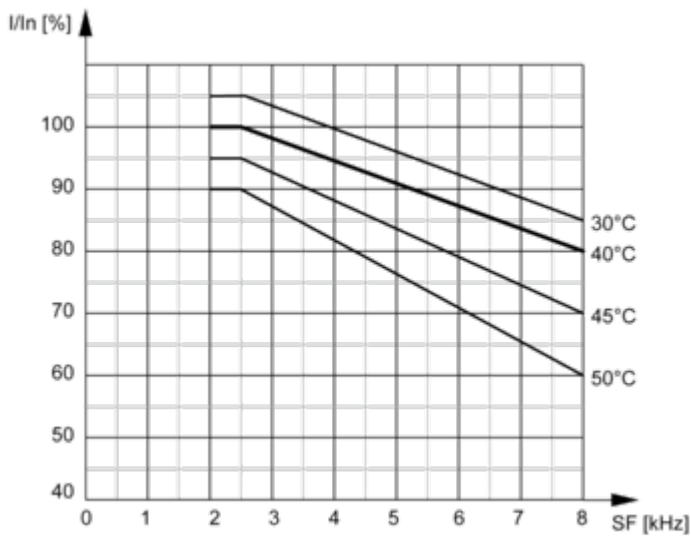
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Normal Duty



In : Nominal Drive Current  
 SF : Switching Frequency

Heavy Duty



In : Nominal Drive Current  
 SF : Switching Frequency