

# Product datasheet

Specifications



Variable speed drive. Altivar  
Process ATV900. floor standing  
ATV950. 250 kW. 400/440 V. w/o  
braking unit. IP54

ATV950C25N4F

**Price: 815,678.66 ZAR**

## Main

|   |  |
|---|--|
| <b>Range Of Product</b>                   | Altivar Process ATV900   |
| <b>Device Application</b>                 | Industrial application   |
| <b>Product Or Component Type</b>          | Variable speed drive   |
| <b>Product Destination</b>                | Asynchronous motors<br>Synchronous motors  |
| <b>Product Specific Application</b>       | Process for industrial   |
| <b>Variant</b>                            | With load break switch<br>Without braking chopper  |
| <b>Network Number Of Phases</b>           | 3 phases   |
| <b>Mounting Mode</b>                      | Floor-standing   |
| <b>Communication Port Protocol</b>        | Modbus TCP<br>Modbus serial<br>EtherNet/IP   |
| <b>[Us] Rated Supply Voltage</b>          | 380...440 V - 15...10 %  |
| <b>Motor Power Kw</b>                     | 250.0 kW for normal duty<br>200.0 kW for heavy duty  |
| <b>Continuous Output Current</b>          | 477 A at 2.5 kHz for normal duty<br>370 A at 2.5 kHz for heavy duty  |
| <b>Emc Filter</b>                         | Integrated<br>With EMC plate option  |
| <b>Ip Degree Of Protection</b>            | IP54   |
| <b>Option Module</b>                      | Slot A: communication module for Profibus DP V1<br>Slot A: communication module for PROFINET<br>Slot A: communication module for DeviceNet<br>Slot A: communication module for EtherCAT<br>Slot A: communication module for CANopen daisy chain RJ45<br>Slot A: communication module for CANopen SUB-D 9<br>Slot A: communication module for CANopen screw terminals<br>Slot A/slot B/slot C: digital and analog I/O extension module<br>Slot A/slot B/slot C: output relay extension module<br>Slot B: 5/12 V digital encoder interface module<br>Slot B: analog encoder interface module<br>Slot B: resolver encoder interface module<br>communication module for Ethernet Powerlink |
| <b>Discrete Input Logic</b>               | 16 preset speeds   |
| <b>Asynchronous Motor Control Profile</b> | Variable torque standard<br>Optimized torque mode<br>Constant torque standard  |
| <b>Synchronous Motor Control Profile</b>  | Permanent magnet motor<br>Synchronous reluctance motor   |
| <b>Maximum Output Frequency</b>           | 599 Hz   |

Excluding VAT and subject to change. Please check with your local distributor through "Where to buy"

|                                    |  |
|------------------------------------|--|
| <b>Switching Frequency</b>         | 2.5..8 kHz with derating factor<br>2..8 kHz adjustable   |
| <b>Nominal Switching Frequency</b> | 2.5 kHz  |
| <b>Line Current</b>                | 453.0 A at 380 V (normal duty)<br>369.0 A at 380 V (heavy duty)<br>391.0 A at 440 V (normal duty)<br>319.0 A at 440 V (heavy duty) |
| <b>Apparent Power</b>              | 299 kVA at 400 V (normal duty)<br>244 kVA at 400 V (heavy duty)  |
| <b>Maximum Transient Current</b>   | 572 A during 60 s (normal duty)<br>555 A during 60 s (heavy duty)  |
| <b>Network Frequency</b>           | 50..60 Hz  |
| <b>Prospective Line Isc</b>        | 50 kA  |

## Complementary

|                                  |  |
|----------------------------------|--|
| <b>Discrete Input Number</b>     | 10   |
| <b>Discrete Input Type</b>       | DI1...DI8 programmable, 24 V DC ( $\leq 30$ V), impedance: 3.5 kOhm<br>DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC ( $\leq 30$ V)<br>STOA, STOB safe torque off, 24 V DC ( $\leq 30$ V), impedance: $> 2.2$ kOhm   |
| <b>Discrete Output Number</b>    | 2  |
| <b>Discrete Output Type</b>      | Logic output DQ+ 0...1 kHz $\leq 30$ V DC 100 mA<br>Programmable as pulse output DQ+ 0...30 kHz $\leq 30$ V DC 20 mA<br>Logic output DQ- 0...1 kHz $\leq 30$ V DC 100 mA   |
| <b>Analogue Input Number</b>     | 3  |
| <b>Analogue Input Type</b>       | AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits<br>AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits   |
| <b>Analogue Output Number</b>    | 2  |
| <b>Analogue Output Type</b>      | Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits<br>Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits   |
| <b>Relay Output Number</b>       | 3  |
| <b>Relay Output Type</b>         | Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles<br>Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles<br>Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles   |
| <b>Maximum Switching Current</b> | Relay output R1 on resistive load, $\cos \phi = 1$ : 3 A at 250 V AC<br>Relay output R1 on resistive load, $\cos \phi = 1$ : 3 A at 30 V DC<br>Relay output R1 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC<br>Relay output R1 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC<br>Relay output R2, R3 on resistive load, $\cos \phi = 1$ : 5 A at 250 V AC<br>Relay output R2, R3 on resistive load, $\cos \phi = 1$ : 5 A at 30 V DC<br>Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC<br>Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC |
| <b>Minimum Switching Current</b> | Relay output R1, R2, R3: 5 mA at 24 V DC   |
| <b>Physical Interface</b>        | Ethernet<br>2-wire RS 485  |
| <b>Connector Type</b>            | 2 RJ45<br>1 RJ45   |
| <b>Method Of Access</b>          | Slave Modbus TCP   |
| <b>Transmission Rate</b>         | 10, 100 Mbits<br>4.8 kbps<br>9600 bit/s<br>19200 bit/s   |

|   |  |
|---|--|
| <b>Transmission Frame</b>                                   | RTU  |
| <b>Number Of Addresses</b>                                  | 1...247  |
| <b>Data Format</b>  | 8 bits, configurable odd, even or no parity  |
| <b>Type Of Polarization</b>                                 | No impedance   |
| <b>4 Quadrant Operation Possible</b>                        | False  |
| <b>Acceleration And Deceleration Ramps</b>                  | Linear adjustable separately from 0.01...9999 s  |
| <b>Motor Slip Compensation</b>                              | Adjustable<br>Automatic whatever the load<br>Not available in permanent magnet motor law<br>Can be suppressed  |
| <b>Braking To Standstill</b>                                | By DC injection  |
| <b>Brake Chopper Integrated</b>                             | False  |
| <b>Maximum Input Current</b>                                | 453.0 A  |
| <b>Maximum Output Voltage</b>                               | 440.0 V  |
| <b>Relative Symmetric Network Frequency Tolerance</b>       | 5 %  |
| <b>Base Load Current At High Overload</b>                   | 370.0 A  |
| <b>Base Load Current At Low Overload</b>                    | 477.0 A  |
| <b>Power Dissipation In W</b>                               | 5750 W, switching frequency 2.5 kHz (normal duty)<br>4340 W, switching frequency 2.5 kHz (heavy duty)  |
| <b>With Safety Function Safely Limited Speed (Sls)</b>      | True   |
| <b>With Safety Function Safe Brake Management (Sbc/Sbt)</b> | True   |
| <b>With Safety Function Safe Operating Stop (Sos)</b>       | False  |
| <b>With Safety Function Safe Position (Sp)</b>              | False  |
| <b>With Safety Function Safe Programmable Logic</b>         | False  |
| <b>With Safety Function Safe Speed Monitor (Ssm)</b>        | False  |
| <b>With Safety Function Safe Stop 1 (Ss1)</b>               | True   |
| <b>With Sft Fct Safe Stop 2 (Ss2)</b>                       | False  |
| <b>With Safety Function Safe Torque Off (Sto)</b>           | True   |
| <b>With Safety Function Safely Limited Position (Slp)</b>   | False  |
| <b>With Safety Function Safe Direction (Sdi)</b>            | False  |
| <b>Protection Type</b>                                      | Thermal protection: motor<br>Safe torque off: motor<br>Motor phase break: motor<br>Thermal protection: drive<br>Safe torque off: drive<br>Overheating: drive<br>Overcurrent between output phases and earth: drive<br>Overload of output voltage: drive<br>Short-circuit protection: drive<br>Motor phase break: drive<br>Overvoltages on the DC bus: drive<br>Line supply overvoltage: drive<br>Line supply undervoltage: drive<br>Line supply phase loss: drive<br>Overspeed: drive<br>Break on the control circuit: drive |
| <b>Quantity Per Set</b>                                     | 1  |
| <b>Width</b>  | 600 mm   |

|                              |  |
|------------------------------|--|
| <b>Height</b>                | 2350 mm  |
| <b>Depth</b>                 | 669 mm   |
| <b>Net Weight</b>            | 500 kg   |
| <b>Electrical Connection</b> | Control: removable screw terminals 0.5...1.5 mm <sup>2</sup><br>Line side: M12 bar<br>Motor: M12 bar   |
| <b>Transmission Rate</b>     | 10/100 Mbit/s for Ethernet IP/Modbus TCP<br>4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial  |
| <b>Exchange Mode</b>         | Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP   |
| <b>Data Format</b>           | 8 bits, configurable odd, even or no parity for Modbus serial  |
| <b>Type Of Polarization</b>  | No impedance for Modbus serial   |
| <b>Number Of Addresses</b>   | 1...247 for Modbus serial  |
| <b>Supply</b>                | External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection<br>Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection<br>Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection |
| <b>Local Signalling</b>      | Local diagnostic: 3 LED (mono/dual colour)<br>Embedded communication status: 5 LED (dual colour)<br>Communication module status: 2 LED (dual colour)<br>Presence of voltage: 1 LED (red)   |
| <b>Input Compatibility</b>   | DI1...DI8: discrete input level 1 PLC conforming to IEC 61131-2<br>DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68<br>STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2  |
| <b>Discrete Input Logic</b>  | Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1)<br>Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1)<br>Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1)<br>Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)   |
| <b>Sampling Duration</b>     | 2 ms +/- 0.5 ms (DI1...DI8) - discrete input<br>5 ms +/- 1 ms (DI7, DI8) - pulse input<br>1 ms +/- 1 ms (AI1, AI2, AI3) - analog input<br>5 ms +/- 1 ms (AQ1, AQ2) - analog output   |
| <b>Accuracy</b>              | +/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input<br>+/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output   |
| <b>Linearity Error</b>       | AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input<br>AQ1, AQ2: +/- 0.2 % for analog output   |
| <b>Refresh Time</b>          | Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)   |
| <b>Isolation</b>             | Between power and control terminals  |

## Environment

|                               |   |
|-------------------------------|---|
| <b>Operating Altitude</b>     | <= 1000 m without derating<br>1000...4800 m with current derating 1 % per 100 m |
| <b>Operating Position</b>     | Vertical +/- 10 degree  |
| <b>Product Certifications</b> | ATEX<br>EAC<br>C-Tick   |
| <b>Marking</b>                | CE  |
| <b>Standards</b>              | IEC 60204-1<br>IEC 61800-2<br>IEC 61800-3<br>IEC 61800-5-1                      |
| <b>Maximum Thdi</b>           | <48 % full load conforming to IEC 61000-3-12                                    |
| <b>Assembly Style</b>         | In floor-standing enclosure   |

|   |  |
|---|--|
| <b>Electromagnetic Compatibility</b>                                    | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2<br>Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3<br>Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4<br>1.2/50 $\mu$ s - 8/20 $\mu$ s surge immunity test level 3 conforming to IEC 61000-4-5<br>Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 |
| <b>Environmental Class (During Operation)</b>                           | Class 3C3 according to IEC 60721-3-3<br>Class 3S3 according to IEC 60721-3-3   |
| <b>Maximum Acceleration Under Shock Impact (During Operation)</b>       | 150 m/s <sup>2</sup> at 11 ms  |
| <b>Maximum Acceleration Under Vibrational Stress (During Operation)</b> | 10 m/s <sup>2</sup> at 13...200 Hz   |
| <b>Maximum Deflection Under Vibratory Load (During Operation)</b>       | 1.5 mm at 2...13 Hz  |
| <b>Permitted Relative Humidity (During Operation)</b>                   | Class 3K5 according to EN 60721-3  |
| <b>Volume Of Cooling Air</b>  | 1300 m <sup>3</sup> /h   |
| <b>Overvoltage Category</b>   | III  |
| <b>Regulation Loop</b>  | Adjustable PID regulator   |
| <b>Insulation Resistance</b>  | > 1 MOhm 500 V DC for 1 minute to earth  |
| <b>Noise Level</b>  | 70 dB conforming to 86/188/EEC   |
| <b>Vibration Resistance</b>   | 1.5 mm peak to peak (f= 2... 13 Hz) conforming to IEC 60068-2-6<br>1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6   |
| <b>Shock Resistance</b>   | 15 gn for 11 ms conforming to IEC 60068-2-27   |
| <b>Environmental Characteristic</b>                                     | Chemical pollution resistance class 3C3 conforming to IEC 60721-3-3<br>Dust pollution resistance class 3S3 conforming to IEC 60721-3-3   |
| <b>Relative Humidity</b>  | 5...95 % without condensation conforming to IEC 60068-2-3  |
| <b>Ambient Air Temperature For Operation</b>                            | -15...40 °C (without derating)<br>40...50 °C (with derating factor)  |
| <b>Noise Level</b>  | 70 dB  |
| <b>Pollution Degree</b>   | 2  |
| <b>Ambient Air Transport Temperature</b>                                | -40...70 °C  |
| <b>Ambient Air Temperature For Storage</b>                              | -40...70 °C  |

## Packing Units

|                                     |          |
|-------------------------------------|----------|
| <b>Unit Type Of Package 1</b>       | PCE      |
| <b>Number Of Units In Package 1</b> | 1        |
| <b>Package 1 Height</b>             | 238.5 cm |
| <b>Package 1 Width</b>              | 120.0 cm |
| <b>Package 1 Length</b>             | 110.0 cm |
| <b>Package 1 Weight</b>             | 550.0 kg |

## Sustainability

**Green Premium™ label** is Schneider Electric's commitment to delivering products with best-in-class environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO<sub>2</sub> products.

**Guide to assessing product sustainability** is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

[Learn more about Green Premium >](#)

[Guide to assess a product's sustainability >](#)



Take-back

## Resource performance

✓ Take-Back Program Available

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## Well-being performance

✓ Mercury Free

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✓ Rohs Exemption Information Yes

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Reach Regulation [REACH Declaration](#)

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Eu Rohs Directive Pro-active compliance (Product out of EU RoHS legal scope)

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China Rohs Regulation [China RoHS declaration](#)

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Weee The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

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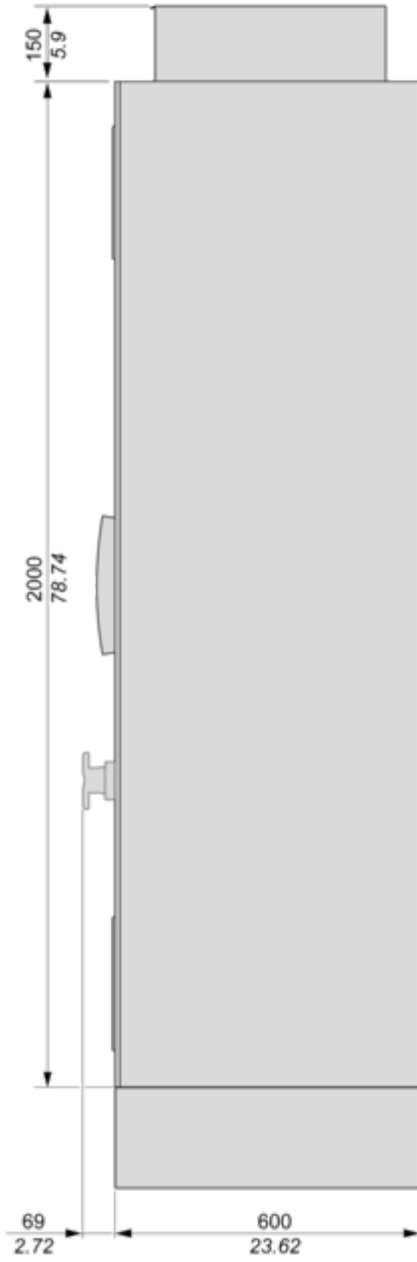
Dimensions Drawings

**Dimensions**

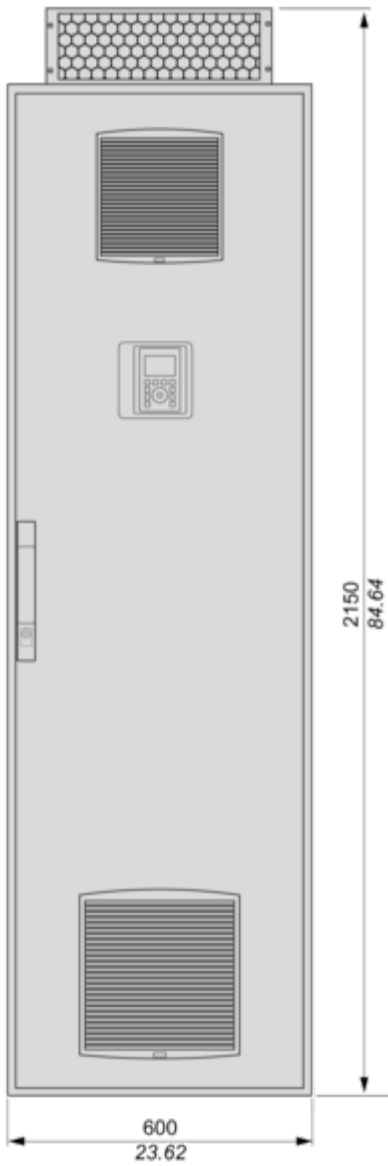
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Right and Front View

mm  
in.



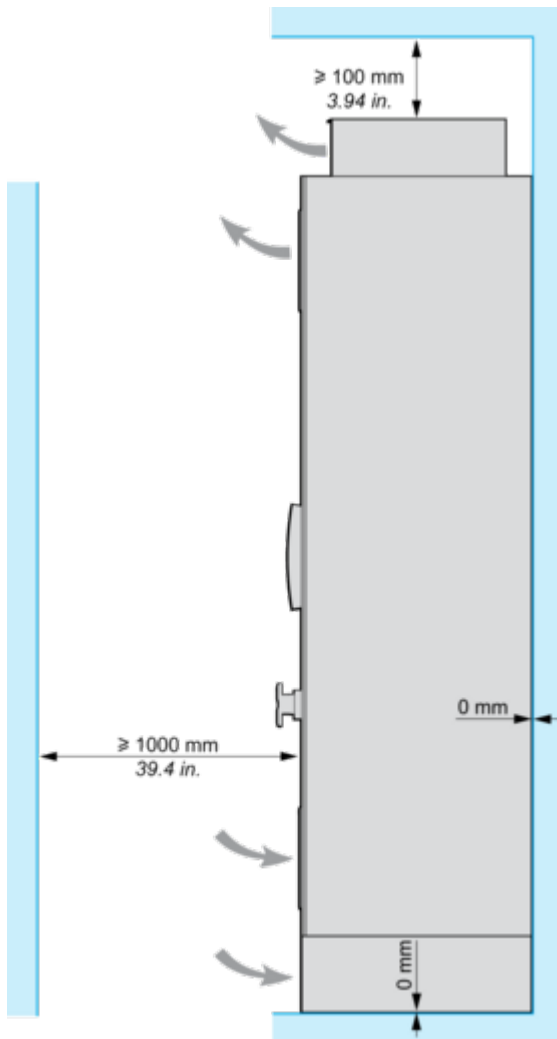
mm  
in.



Mounting and Clearance

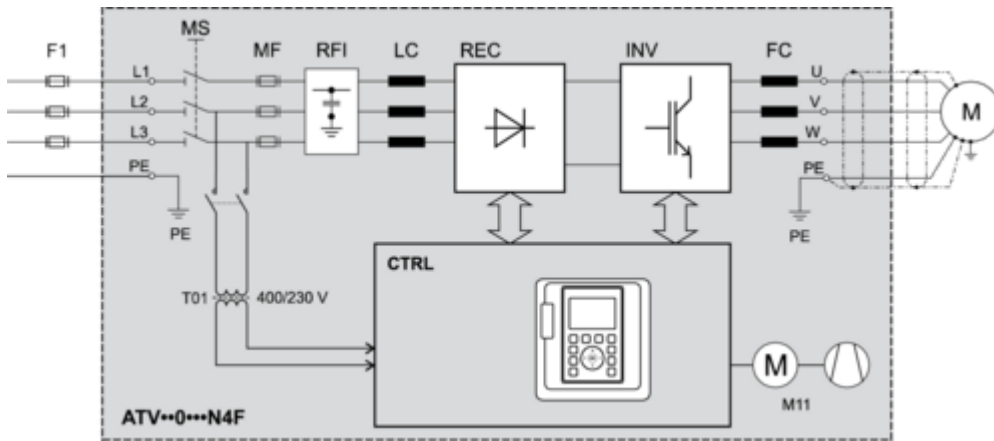
Clearances

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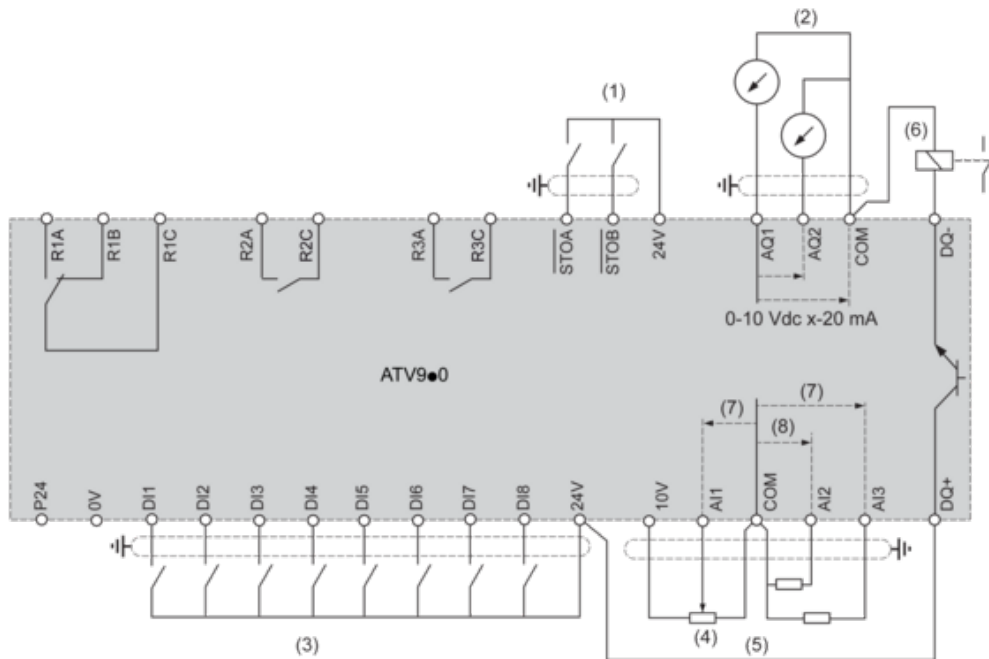
Connections and Schema

Floor Standing Drive Circuit Diagram



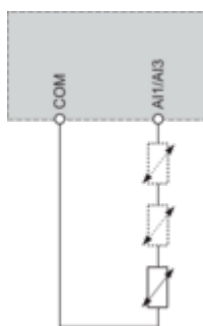
- F1** External pre-fuse or circuit breaker
- MS** Built-in main switch (only available on IP54 drives)
- T01** Control transformer 400 / 230 V AC
- MF** aR fuses
- RFI** Built-in RFI filter
- LC** Line reactor choke
- REC** Rectifier module
- INV** Inverter module
- FC** dv/dt filter (from 355 kW the dv/dt filter choke 150 m is built-in as standard)
- CTRL** Control panel
- M11** Fan in enclosure door

Control Block Wiring Diagram



- (1) Safe Torque Off
  - (2) Analog Output
  - (3) Digital Input
  - (4) Reference potentiometer
  - (5) Analog Input
  - (6) Digital Output
  - (7) 0-10 Vdc, x-20 mA
  - (8) 0-10 Vdc, -10 Vdc...+10 Vdc
- R1A, R1B, R1C** : Fault relay  
**R2A, R2C** : Sequence relay  
**R3A, R3C** : Sequence relay

Sensor Connection



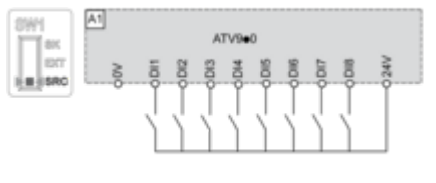
It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

**Sink / Source Switch Configuration**

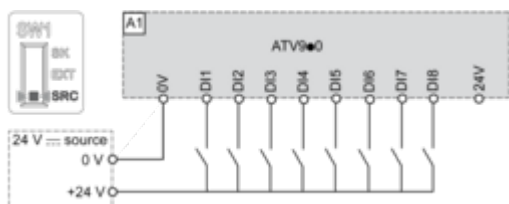
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

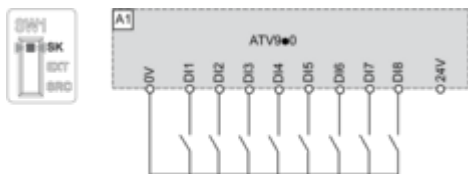
**Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs**



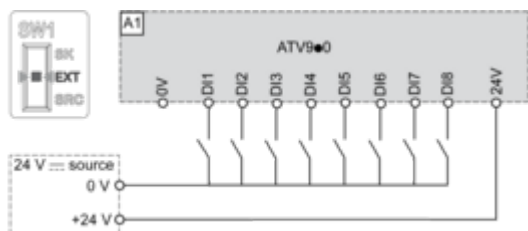
**Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs**



**Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs**



**Switch Set to EXT Position Using an External Power Supply for the DIs**

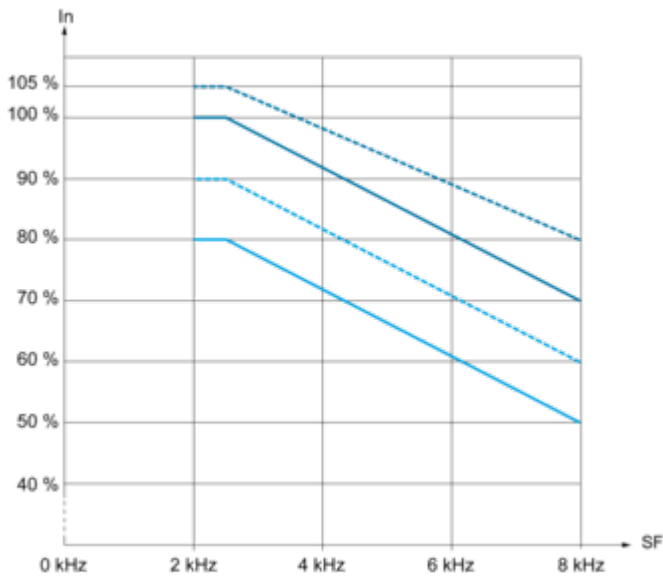


Performance Curves

Derating Curves

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Normal Duty

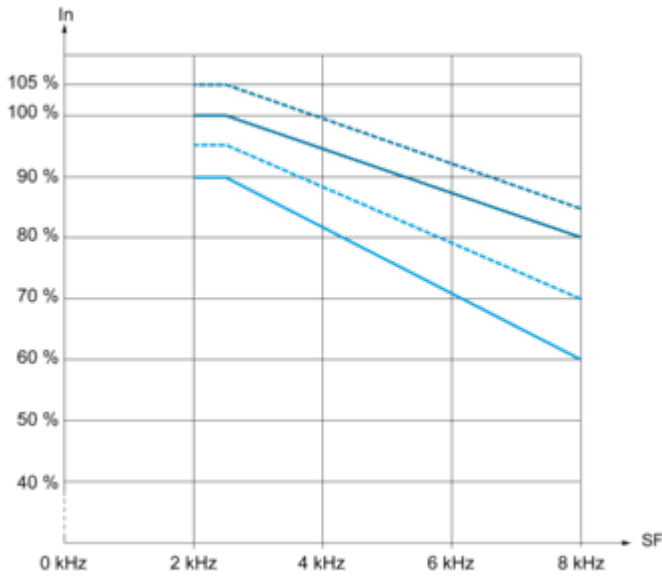


- 30 °C (86 °F)
  - 40 °C (104 °F)
  - 45 °C (122 °F)
  - 50 °C (140 °F)
- In : Nominal Drive Current  
SF : Switching Frequency

Derating Curves

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Heavy Duty



- 30 °C (86 °F)
  - 40 °C (104 °F)
  - 45 °C (122 °F)
  - 50 °C (140 °F)
- In : Nominal Drive Current  
SF : Switching Frequency